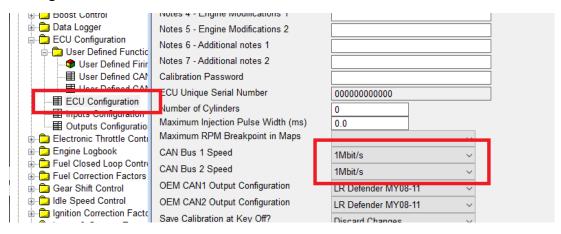
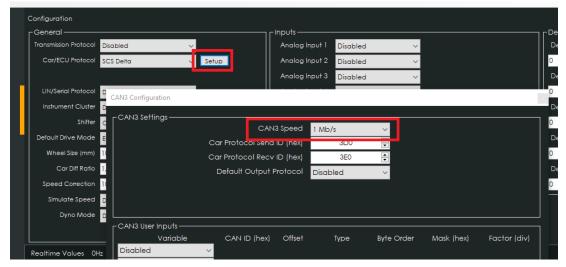
## CANTCU – SCS Delta Integration

- Delta 700, 880, 900 and GDI6 ECUs with FW 01.06.2023 or newer
- CAN2.0B, Standard 11bit identifiers
- CAN Speed is configurable
- CAN I/O Addressing is configurable

### SCS Delta CAN Configuration

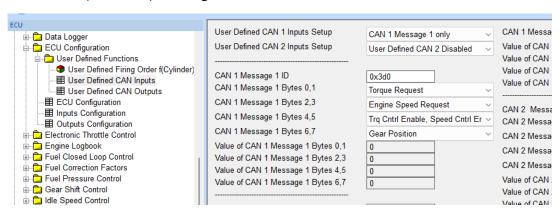
Select a matching CAN speed/frequency in both SXTune and CANTCU Configurator.



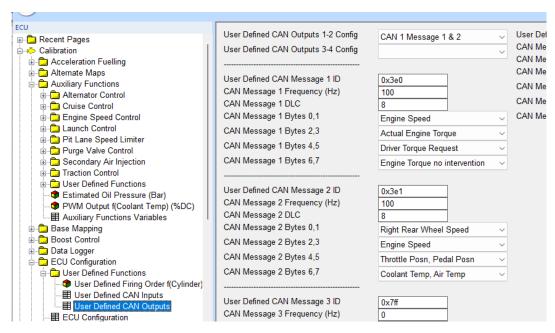




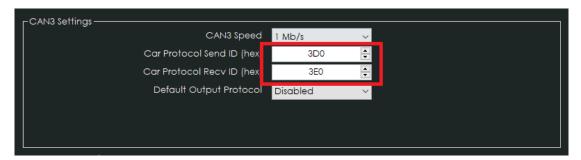
User defined CAN Inputs settings as below. Note that CAN 1 is selected, change to CAN 2 if required depending on which ECU CAN bus the CANTCU is connected to.



User defined CAN output settings as below. Note that CAN 1 is selected, change to CAN 2 if required depending on which ECU CAN bus the CANTCU is connected to.



Match the CANTCU **Send ID** and **Recv ID** to IDs used in SXTune.





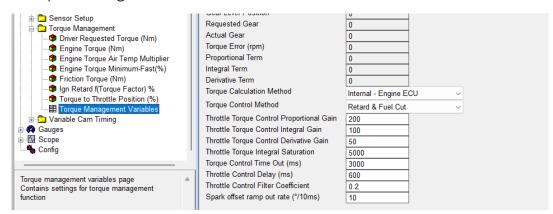
### Torque Management Settings

#### NOTE!

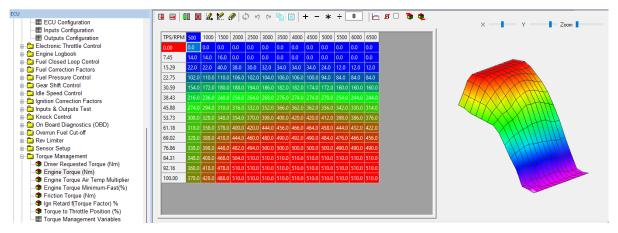
# All tuning should always be done by a professional in a safe environment (track/dyno)

RPM Targeting (blips) on downshifts needs to be carefully tuned to avoid undesired behavior (overshoot/undershoot) of the blip. Especially on DCT transmissions, the RPM request sent from CANTCU to SCS Delta is heavily dependent on a correctly calibrated diff ratio/wheelspeed.

In Torque Management, set variables as below:

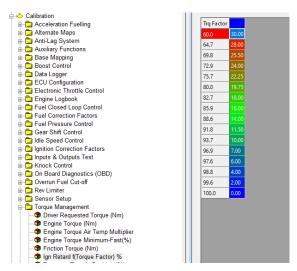


Example Engine Torque map. This map should be calibrated on a dyno or rolling road, and it can be estimated from a full load power curve. If transmission slip is experienced on low/medium load, increase the values in corresponding part of the map.

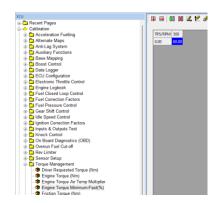




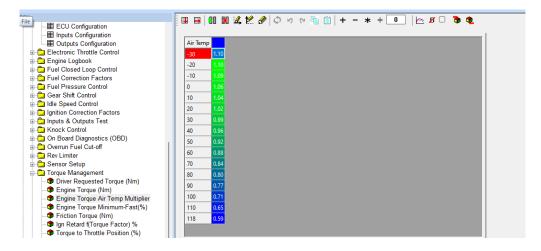
Ignition Retard f(Torque Factor) %. If torque reduction on upshifts feel too aggressive/excessive, decrease the values in this map.



### Engine Torque Minimum-Fast(%)



### Engine Torque Air Temp Multiplier





### Friction Torque example map

